

FIG. 2

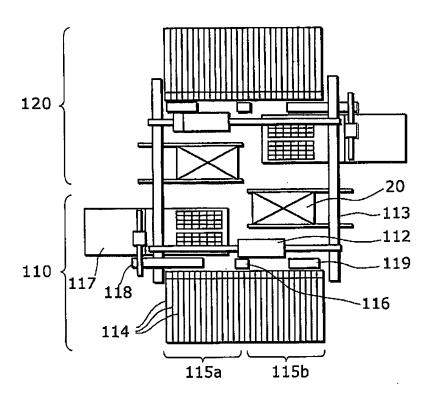


FIG. 3

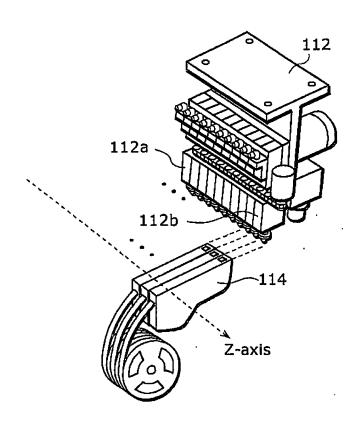
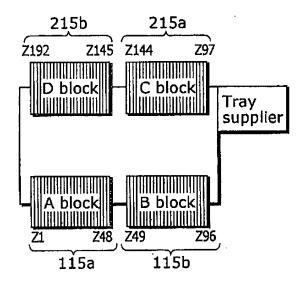


FIG. 4A



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FIG. 4B

											_	_	_	
			Occupied consecutive positions	F	1	1	2	2	2	3	4	4		
			247 tapes 249 Z51 Z93 Z95 tapes 297 Z99 Z141 Z143 tapes 2145 Z147 Z189 Z191 tapes positions	192	96	96	48	48	48	32	24	24		
	7102	76	No. of tapes	48	24	24	12	12	12	8	9	9		
	ř		7191	0	0	0	0	0	0	1	1	ı		
	Ľ	,	Z189	0	0	0	0	0	0	0	0	0		
	711F	† <u> </u>	2147	0	0	0	0	0	0	0	0	0		
			2145	0	0	0	0	0	0	ī	ī	ī		П
	7111		No. of	48	24	24	12	12	12	æ	9	9		
	7.4	7	5.	0	0	0	0	0	0		ı	ī		
S	,		1141	0	0	0	0	0	0	0	0	0		7
	0	67	85	0	0	0	0	0	0	0	0	0		1
L	L		762	0	0	0	0	0	0	ı	ı	1		1
	٤	0 2 2	No. of tapes	48	24	24	12	12	12	80	9	9		
В			262	000	0	0	0	0	0	1	ļ	1	4	
	2	2	<u> </u>	0	0	0	0	0	0	0	0	0	\parallel	
	ļ	24.5	25		0	0	0	0	0	0	0	0		
<u> </u>	9	24 25 26	of Z4	48	24 0	24 C	12 0	12 0	12 0	8	9	- 9		
	ŀ		S is	_	ᆫ	L	Ļ	<u> </u>		Ļ	Ļ	L	1	
⋖			5 24	0	0	0	0	0	0	<u> </u>	Ľ	-	1	
	7	7	Z1 Z3 Z45	10	6	6	6	6	6	6	6	6	ł	
L	L			Ö	Ö	00	00	00	0	1	Ī	Ī	1	
			Tape	8(Double) O O	8(Single) OO	12	16	24	1	44	26	72		•
			Component cassettes											

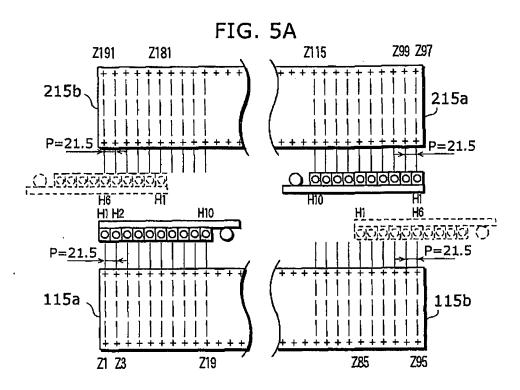


FIG. 5B

10 nozzle	Inner side	Z1 Z2	Z3 Z4	Z5 Z6	Z7 Z8	Z9 Z10	Z11 Z12	Z13 Z14	Z15 Z16	Z17 Z18	Z19 ~ Z86	Z87 Z88	Z89 Z90	Z91 Z92	Z93 Z94	Z95 Z96
heads	Outer side	Z97 Z98	Z99 Z100	Z101 Z102	Z103 Z104	Z105 Z106	Z107 Z108	Z109 Z110	Z111 Z112	Z113 Z114	Z115 ~ Z182	Z183 Z184	Z185 Z186	Z187 Z188	Z189 Z190	Z191 Z192
	H1	0	0	0	0	0	0	0	0	0	0	i	1		I	-
	H2	ī	0	0	0	0	0	0	0	0	0	0	-			1
	H3	=		0	0	0	0	0	0	0	0	0	0		1	1
	H4	-	-	=	0	0	0	0	0	0	0	0	0	0	_	1
Heads	H5		=	_	-	0	0	0	0	0	0	0	0	0	0	
(Nozzles)	H6	-	-	_	-	-	0	0	0	0	0	0	0	O.	0	0
	H7	_	-	-	_		1	0	0	0	0	0	0	0	0	0
	H8	_	_	-	=		1	_	0	0	0	0	0	0	0	0
	H9	_	-	_		-	_		-	Ó	0	0	0	0	0	0
	H10		_				_	_		_	0	0	0	0	0	0

O: Picking up possible-: Picking up impossible

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FIG. 6A FIG. 6B FIG. 6C FIG. 6D

FIG. 7

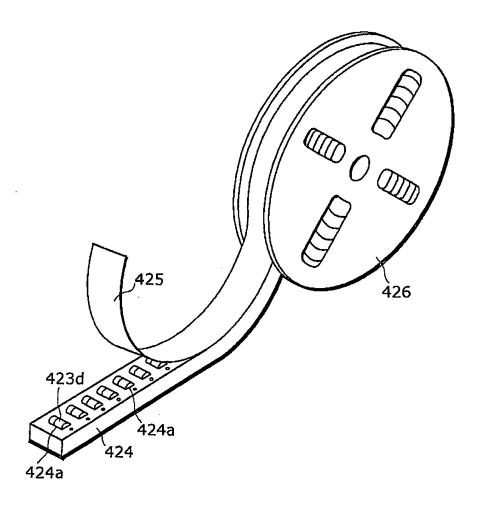
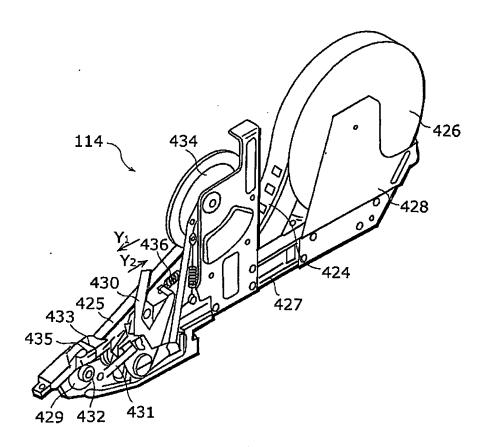
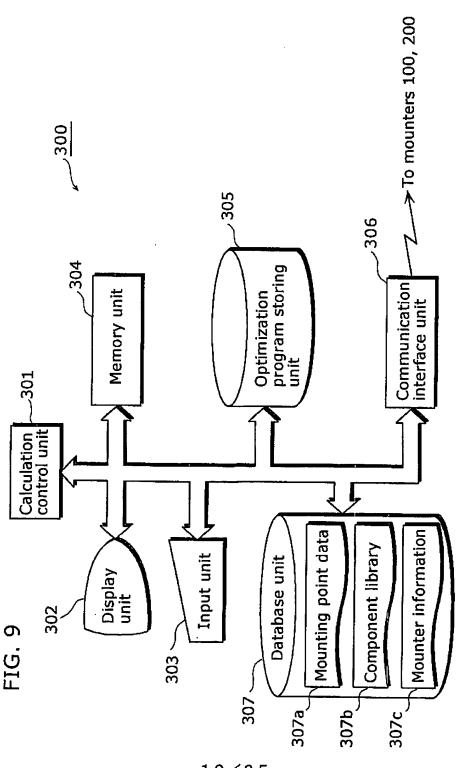


FIG. 8



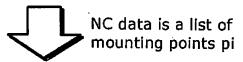


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FIG. 10

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Mounting points $pi=(Component type Ci, X coordinate Xi, Y coordinate Yi, Mounting angle <math>\theta$ i, Control data ϕ i)



NC data =
$$\begin{pmatrix} p1 \\ p2 \\ p3 \\ \vdots \\ pN \end{pmatrix}$$
 = $\begin{pmatrix} c1, x1, y1, \theta1, \phi1 \\ c2, x2, y2, \theta2, \phi2 \\ c3, x3, y3, \theta3, \phi3 \\ \vdots \\ cN, xN, yN, \thetaN, \phiN \end{pmatrix}$

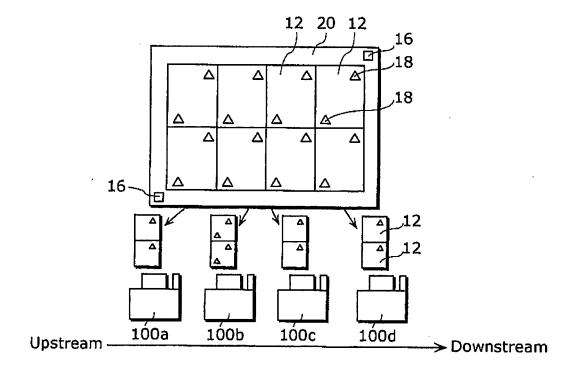
FIG. 11 307b Component 2-D Tact Component (Appea-Pick-up Speed size (mm) time recognition (sec.) XY name rance) nozzle method X 0603CR 0.6 0.3 SX 0.25 0.086 1005CR SA 1.0 0.5 0.3-0.5 1608CR 0.8 0.4-0.8 0.094 1.6 2.0 1.25 0.4-0.8 2012CR S 3216CR 3.2 1.6 0.4-0.8 1 4TR 2.8 2.8 1.1 6TR 4.3 4.5 1.5 Cylindrical 1TIP $2.0|\phi 1.0$ tip 2TIP $3.6 \phi 1.4$ 0.11 1CAP 3.8 1.9 1.6 S 2CAP 2.6 2.1 4.7 3CAP 6.0 3.2 2.5 Reflection 4.3 4CAP 7.3 2.8 Μ SCAP 4.3 4.3 6.0 LCAP 6.6 6.6 6.0 LLCAP 10.3l 10.3 10.5 ML 1VOL 4.5 3.8 1.6-2.4 2VOL 3.7 3.0 1.6 M 0.13 2 3VOL 4.8 3.0 4.0

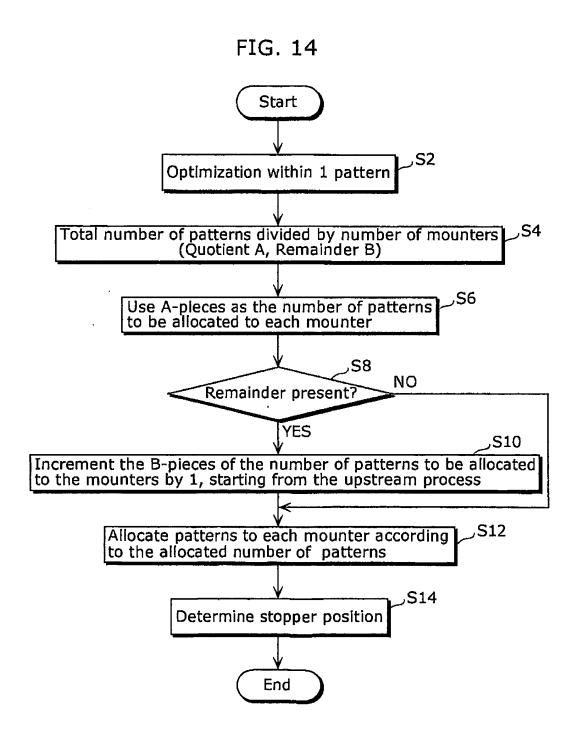
FIG. 12

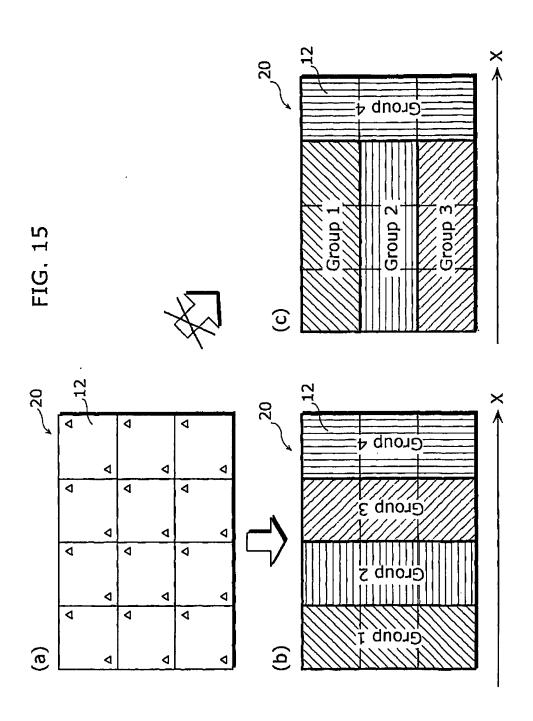
_307c

8 levels
None
None

FIG. 13

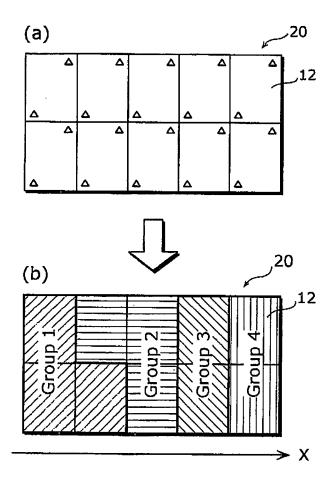


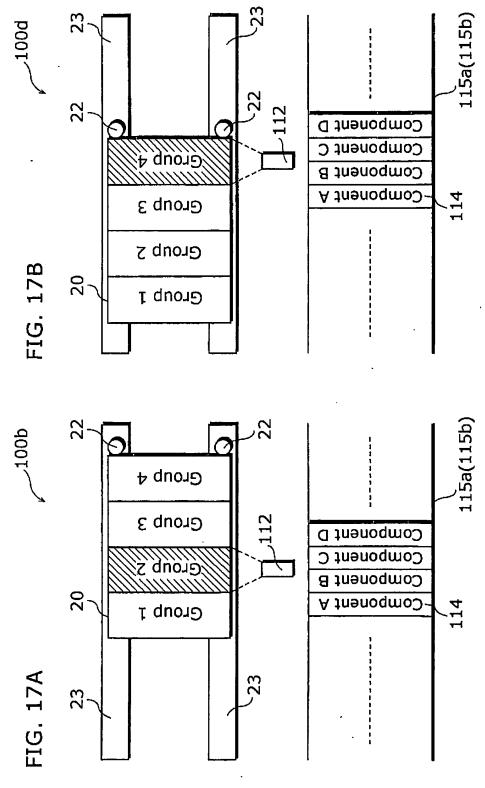


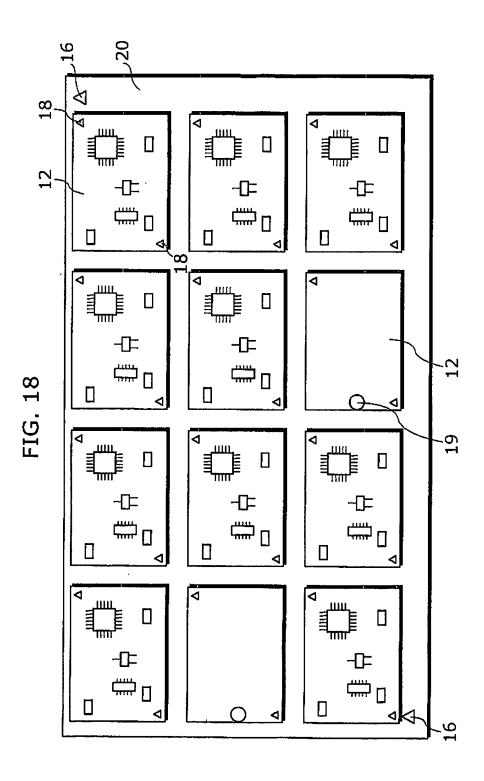


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FIG. 16







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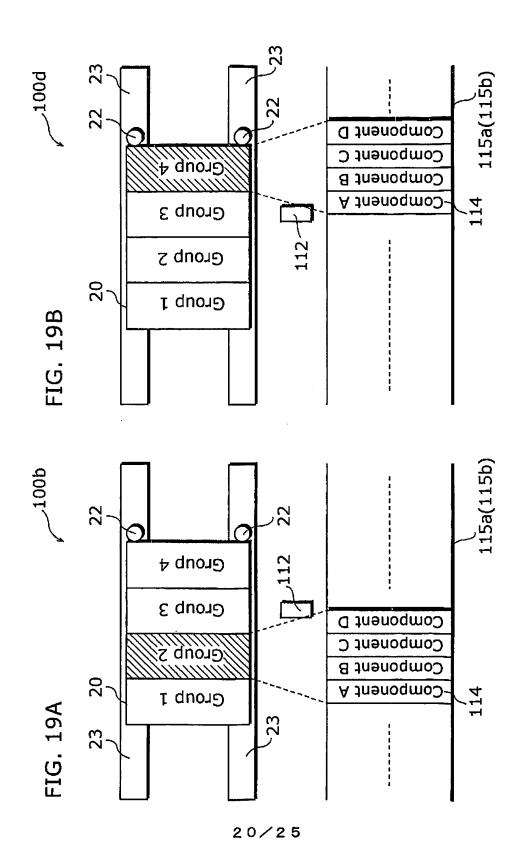


FIG. 20

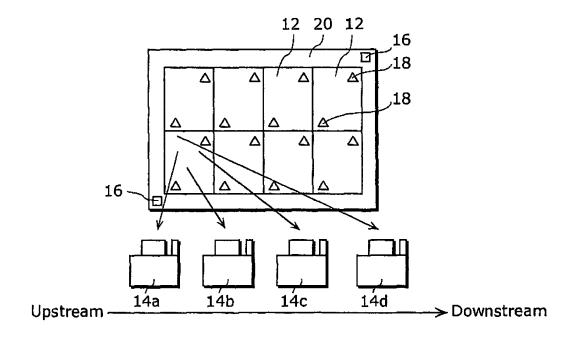
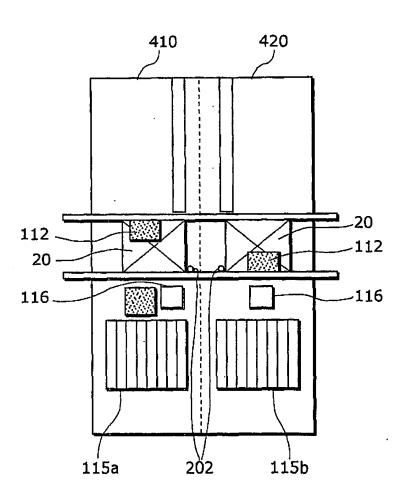
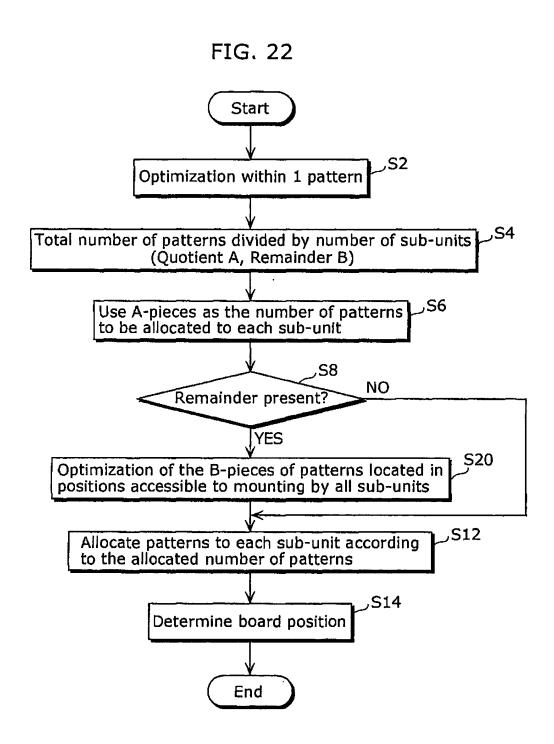
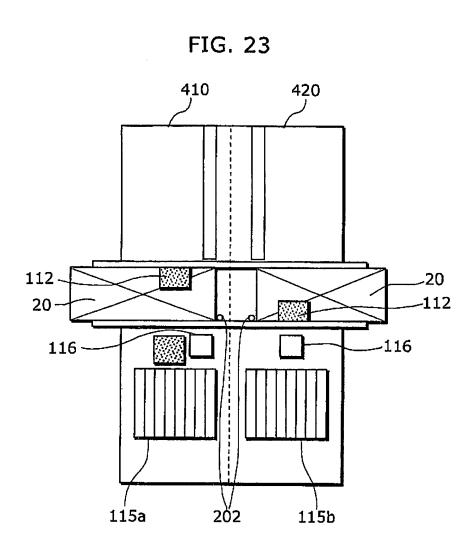


FIG. 21





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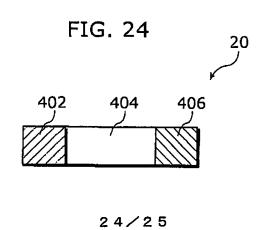


FIG. 25

